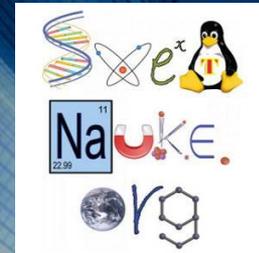




fizika.pmf.ni.ac.rs



svetnauke.org

Fizika mobilnog telefona

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Prezentacija radova „Mobilni telefon u fizičkom eksperimentu“
20. april 2019, PMF, Niš

Zadatak za razmišljanje 😊

- Koristeći materijal dostupan u kući/amfiteatru izmeriti obim Zemlje...



Istorija

- 1873. – J. Maksvel – teorija elektromagnetizma
- 1876. – A. Bel – prvi telefon (takođe prvi „fotofon“ – preteča bežičnih telefona)
- 1888. – H. Herc – prvi elektromagnetni talasi i laboratoriji
- 1894. – O. Lodž – prva poruka preko radio talasa (Oksford)
- 1899. – G. Markoni – prva poruka preko Engleskog kanala (1901. preko Atlantika)
- 1906. – R. Fesenden – prva glasovna poruka
- 1920-te - Hitne službe počinju da koriste bežične telefone

Istorija

- 1940-te – mobilni telefoni postaju popularni u hitnim i taksi službama
- 1946. – AT&T predstavio svoj Mobile Telephone System (MTS) za slanje radio signala između vozila
- 1960-te – Bellve laboratorije razvijaju mobilne telefone za vozove
- 1973. M. Kuper (Motorola) predstavio prvi prenosni mobilni telefon (patent 1975.)

Fizika mobilnog telefona

- Maksvelove jednačine

$$\begin{aligned}\oiint_{\partial\Omega} \vec{E} \cdot d\vec{S} &= \frac{1}{\epsilon_0} \iiint_{\Omega} \rho dV & \nabla \cdot \vec{E} &= \frac{\rho}{\epsilon_0} \\ \oiint_{\partial\Omega} \vec{B} \cdot d\vec{S} &= 0 & \nabla \cdot \vec{B} &= 0 \\ \oint_{\partial\Sigma} \vec{E} \cdot d\vec{l} &= -\frac{d}{dt} \iint_{\Sigma} \vec{B} \cdot d\vec{S} & \nabla \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\ \oint_{\partial\Sigma} \vec{B} \cdot d\vec{l} &= \mu_0 \iint_{\Sigma} \vec{J} \cdot d\vec{S} + \mu_0 \epsilon_0 \frac{d}{dt} \iint_{\Sigma} \vec{E} \cdot d\vec{S} & \nabla \times \vec{B} &= \mu_0 \left(\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)\end{aligned}$$

- Šredingerova jednačina

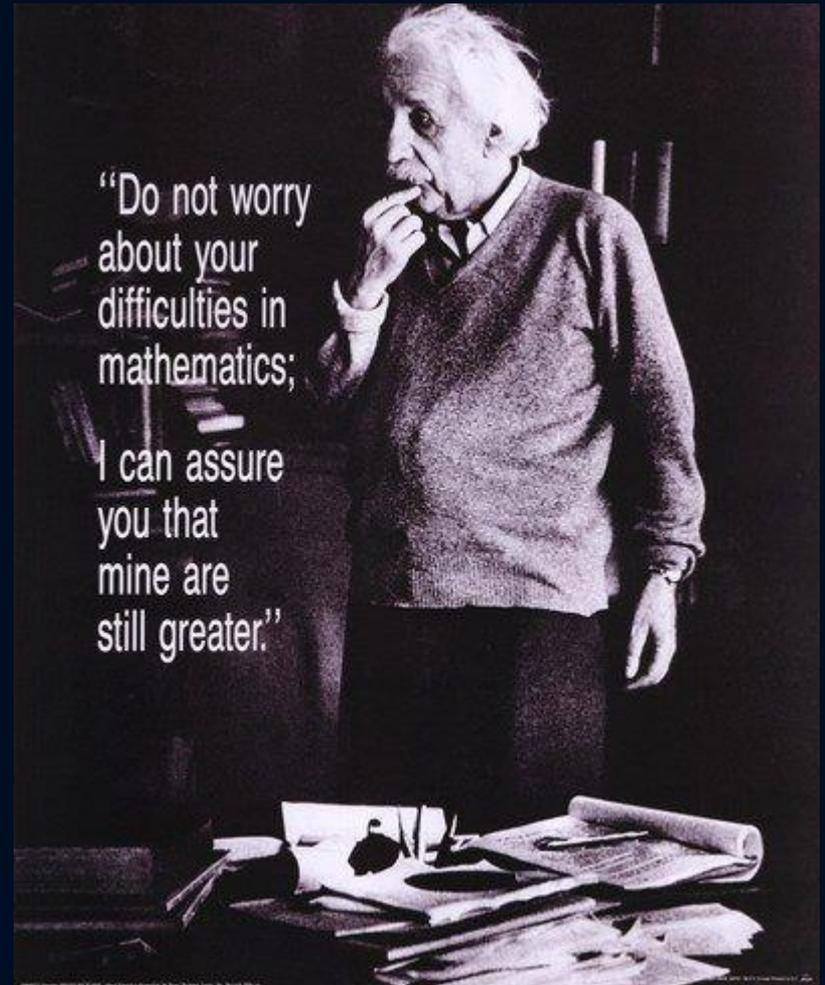
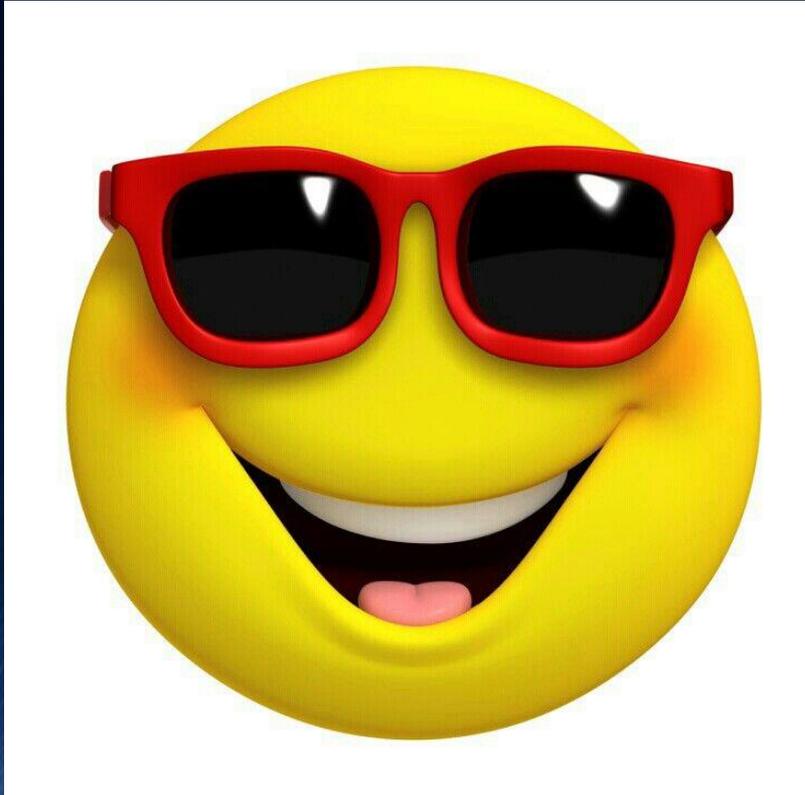
$$i\hbar \frac{\partial}{\partial t} \psi(\vec{r}, t) = \left[\frac{-\hbar^2}{2\mu} \nabla^2 + V(\vec{r}, t) \right] \psi(\vec{r}, t)$$

- Opšta teorija relativnosti

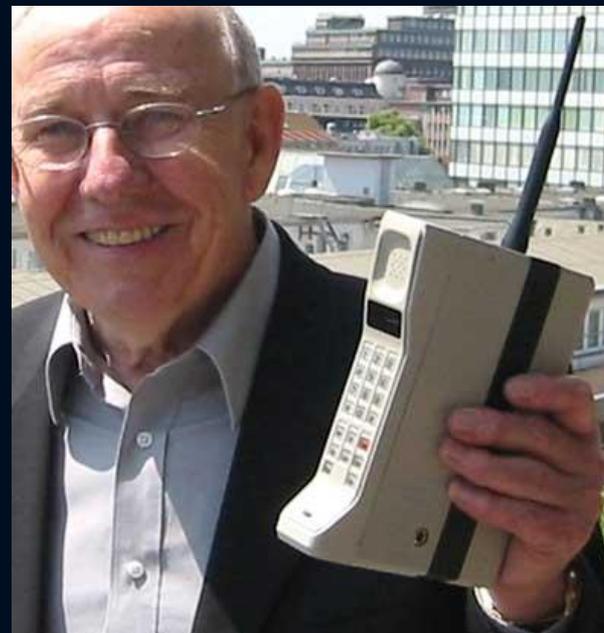
$$G_{\mu\nu} \equiv R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = \frac{8\pi G}{c^4} T_{\mu\nu}$$

Lagranžijan Standardnog modela

$$\begin{aligned}
 \mathcal{L}_{SM} = & -\frac{1}{2}\partial_\nu g_\mu^a \partial_\nu g_\mu^a - g_s f^{abc} \partial_\mu g_\nu^a g_\mu^b g_\nu^c - \frac{1}{4}g_s^2 f^{abc} f^{ade} g_\mu^a g_\nu^b g_\mu^c g_\nu^d - \partial_\nu W_\mu^+ \partial_\nu W_\mu^- - \\
 & M^2 W_\mu^+ W_\mu^- - \frac{1}{2}\partial_\nu Z_\mu^0 \partial_\nu Z_\mu^0 - \frac{1}{2c_w^2} M^2 Z_\mu^0 Z_\mu^0 - \frac{1}{2}\partial_\mu A_\nu \partial_\mu A_\nu - ig_{c_w} (\partial_\nu Z_\mu^0 (W_\mu^+ W_\nu^- - \\
 & W_\nu^+ W_\mu^-) - Z_\nu^0 (W_\mu^+ \partial_\nu W_\mu^- - W_\mu^- \partial_\nu W_\mu^+)) + Z_\mu^0 (W_\nu^+ \partial_\nu W_\mu^- - W_\nu^- \partial_\nu W_\mu^+) - \\
 & ig_{s_w} (\partial_\nu A_\mu (W_\mu^+ W_\nu^- - W_\nu^+ W_\mu^-) - A_\nu (W_\mu^+ \partial_\nu W_\mu^- - W_\mu^- \partial_\nu W_\mu^+) + A_\mu (W_\nu^+ \partial_\nu W_\mu^- - \\
 & W_\nu^- \partial_\nu W_\mu^+)) - \frac{1}{2}g^2 W_\mu^+ W_\mu^- W_\nu^+ W_\nu^- + \frac{1}{2}g^2 W_\mu^+ W_\nu^- W_\mu^+ W_\nu^- + g^2 c_w^2 (Z_\mu^0 W_\mu^+ Z_\nu^0 W_\nu^- - \\
 & Z_\mu^0 Z_\nu^0 W_\mu^+ W_\nu^-) + g^2 s_w^2 (A_\mu W_\mu^+ A_\nu W_\nu^- - A_\mu A_\nu W_\mu^+ W_\nu^-) + g^2 s_w c_w (A_\mu Z_\nu^0 (W_\mu^+ W_\nu^- - \\
 & W_\nu^+ W_\mu^-) - 2A_\mu Z_\mu^0 W_\nu^+ W_\nu^-) - \frac{1}{2}\partial_\mu H \partial_\mu H - 2M^2 \alpha_h H^2 - \partial_\mu \phi^+ \partial_\mu \phi^- - \frac{1}{2}\partial_\mu \phi^0 \partial_\mu \phi^0 - \\
 & \beta_h \left(\frac{2M^2}{g^2} + \frac{2M}{g} H + \frac{1}{2}(H^2 + \phi^0 \phi^0 + 2\phi^+ \phi^-) \right) + \frac{2M^4}{g^2} \alpha_h - \\
 & g\alpha_h M (H^3 + H\phi^0 \phi^0 + 2H\phi^+ \phi^-) - \\
 & \frac{1}{8}g^2 \alpha_h (H^4 + 4(\phi^+ \phi^-)^2 + 4(\phi^0)^2 \phi^+ \phi^- + 4H^2 \phi^+ \phi^- + 2(\phi^0)^2 H^2) - \\
 & gMW_\mu^+ W_\mu^- H - \frac{1}{2}g \frac{M}{c_w} Z_\mu^0 Z_\mu^0 H - \\
 & \frac{1}{2}ig (W_\mu^+ (\phi^0 \partial_\mu \phi^- - \phi^- \partial_\mu \phi^0) - W_\mu^- (\phi^0 \partial_\mu \phi^+ - \phi^+ \partial_\mu \phi^0)) + \\
 & \frac{1}{2}g (W_\mu^+ (H\partial_\mu \phi^- - \phi^- \partial_\mu H) + W_\mu^- (H\partial_\mu \phi^+ - \phi^+ \partial_\mu H)) + \frac{1}{2}g \frac{1}{c_w} (Z_\mu^0 (H\partial_\mu \phi^0 - \phi^0 \partial_\mu H) + \\
 & M (\frac{1}{c_w} Z_\mu^0 \partial_\mu \phi^0 + W_\mu^+ \partial_\mu \phi^- + W_\mu^- \partial_\mu \phi^+) - ig \frac{s_w}{c_w} M Z_\mu^0 (W_\mu^+ \phi^- - W_\mu^- \phi^+) + ig_{s_w} M A_\mu (W_\mu^+ \phi^- - \\
 & W_\mu^- \phi^+) - ig \frac{1-2c_w^2}{2c_w} Z_\mu^0 (\phi^+ \partial_\mu \phi^- - \phi^- \partial_\mu \phi^+) + ig_{s_w} A_\mu (\phi^+ \partial_\mu \phi^- - \phi^- \partial_\mu \phi^+) - \\
 & \frac{1}{4}g^2 W_\mu^+ W_\mu^- (H^2 + (\phi^0)^2 + 2\phi^+ \phi^-) - \frac{1}{8}g^2 \frac{1}{c_w^2} Z_\mu^0 Z_\mu^0 (H^2 + (\phi^0)^2 + 2(2s_w^2 - 1)^2 \phi^+ \phi^-) - \\
 & \frac{1}{2}g^2 \frac{s_w^2}{c_w} Z_\mu^0 \phi^0 (W_\mu^+ \phi^- + W_\mu^- \phi^+) - \frac{1}{2}ig^2 \frac{s_w}{c_w} Z_\mu^0 H (W_\mu^+ \phi^- - W_\mu^- \phi^+) + \frac{1}{2}g^2 s_w A_\mu \phi^0 (W_\mu^+ \phi^- + \\
 & W_\mu^- \phi^+) + \frac{1}{2}ig^2 s_w A_\mu H (W_\mu^+ \phi^- - W_\mu^- \phi^+) - g^2 \frac{s_w}{c_w} (2c_w^2 - 1) Z_\mu^0 A_\mu \phi^+ \phi^- - \\
 & g^2 s_w^2 A_\mu A_\nu \phi^+ \phi^- + \frac{1}{2}ig_s \lambda_{ij}^a (q_i^\sigma \gamma^\mu q_j^\sigma) g_\mu^a - \bar{e}^\lambda (\gamma \partial + m_e^\lambda) e^\lambda - \bar{\nu}^\lambda (\gamma \partial + m_\nu^\lambda) \nu^\lambda - \bar{u}_j^\lambda (\gamma \partial + \\
 & m_u^\lambda) u_j^\lambda - \bar{d}_j^\lambda (\gamma \partial + m_d^\lambda) d_j^\lambda + ig_{s_w} A_\mu (-\bar{e}^\lambda \gamma^\mu e^\lambda) + \frac{2}{3}(\bar{u}_j^\lambda \gamma^\mu u_j^\lambda) - \frac{1}{3}(\bar{d}_j^\lambda \gamma^\mu d_j^\lambda) + \\
 & \frac{ig}{4c_w} Z_\mu^0 \{ (\bar{\nu}^\lambda \gamma^\mu (1 + \gamma^5) \nu^\lambda) + (\bar{e}^\lambda \gamma^\mu (4s_w^2 - 1 - \gamma^5) e^\lambda) + (\bar{d}_j^\lambda \gamma^\mu (\frac{4}{3}s_w^2 - 1 - \gamma^5) d_j^\lambda) + \\
 & (\bar{u}_j^\lambda \gamma^\mu (1 - \frac{8}{3}s_w^2 + \gamma^5) u_j^\lambda) \} + \frac{ig}{2\sqrt{2}} W_\mu^+ ((\bar{\nu}^\lambda \gamma^\mu (1 + \gamma^5) U^{lep}{}_{\lambda\kappa} e^\kappa) + (\bar{u}_j^\lambda \gamma^\mu (1 + \gamma^5) C_{\lambda\kappa} d_j^\kappa)) + \\
 & \frac{ig}{2\sqrt{2}} W_\mu^- ((\bar{e}^\kappa U^{lep}{}_{\kappa\lambda} \gamma^\mu (1 + \gamma^5) \nu^\lambda) + (\bar{d}_j^\kappa C_{\kappa\lambda}^\dagger \gamma^\mu (1 + \gamma^5) u_j^\lambda)) + \\
 & \frac{ig}{2M\sqrt{2}} \phi^+ (-m_e^\lambda (\bar{\nu}^\lambda U^{lep}{}_{\lambda\kappa} (1 - \gamma^5) e^\kappa) + m_\nu^\lambda (\bar{\nu}^\lambda U^{lep}{}_{\lambda\kappa} (1 + \gamma^5) e^\kappa) + \\
 & \frac{ig}{2M\sqrt{2}} \phi^- (m_e^\lambda (\bar{e}^\lambda U^{lep}{}_{\lambda\kappa}^\dagger (1 + \gamma^5) \nu^\kappa) - m_\nu^\lambda (\bar{e}^\lambda U^{lep}{}_{\lambda\kappa}^\dagger (1 - \gamma^5) \nu^\kappa) - \frac{g}{2} \frac{m_\lambda}{M} H (\bar{\nu}^\lambda \nu^\lambda) - \\
 & \frac{g}{2} \frac{m_\lambda}{M} H (\bar{e}^\lambda e^\lambda) + \frac{ig}{2} \frac{m_\lambda^2}{M} \phi^0 (\bar{\nu}^\lambda \gamma^5 \nu^\lambda) - \frac{ig}{2} \frac{m_\lambda^2}{M} \phi^0 (\bar{e}^\lambda \gamma^5 e^\lambda) - \frac{1}{4} \bar{\nu}_\lambda M_{\lambda\kappa}^R (1 - \gamma_5) \hat{\nu}_\kappa - \\
 & \frac{1}{4} \bar{\nu}_\lambda M_{\lambda\kappa}^R (1 - \gamma_5) \hat{\nu}_\kappa + \frac{ig}{2M\sqrt{2}} \phi^+ (-m_d^\lambda (\bar{u}_j^\lambda C_{\lambda\kappa} (1 - \gamma^5) d_j^\kappa) + m_u^\lambda (\bar{u}_j^\lambda C_{\lambda\kappa} (1 + \gamma^5) d_j^\kappa) + \\
 & \frac{ig}{2M\sqrt{2}} \phi^- (m_d^\lambda (\bar{d}_j^\lambda C_{\lambda\kappa}^\dagger (1 + \gamma^5) u_j^\kappa) - m_u^\lambda (\bar{d}_j^\lambda C_{\lambda\kappa}^\dagger (1 - \gamma^5) u_j^\kappa) - \frac{g}{2} \frac{m_\lambda}{M} H (\bar{u}_j^\lambda u_j^\lambda) - \\
 & \frac{g}{2} \frac{m_\lambda}{M} H (\bar{d}_j^\lambda d_j^\lambda) + \frac{ig}{2} \frac{m_\lambda^2}{M} \phi^0 (\bar{u}_j^\lambda \gamma^5 u_j^\lambda) - \frac{ig}{2} \frac{m_\lambda^2}{M} \phi^0 (\bar{d}_j^\lambda \gamma^5 d_j^\lambda) + \bar{G}^a \partial^2 G^a + g_s f^{abc} \partial_\mu \bar{G}^a G^b g_\mu^c + \\
 & \bar{X}^+ (\partial^2 - M^2) X^+ + \bar{X}^- (\partial^2 - M^2) X^- + \bar{X}^0 (\partial^2 - \frac{M^2}{c_w^2}) X^0 + \bar{Y} \partial^2 Y + ig_{c_w} W_\mu^+ (\partial_\mu \bar{X}^0 X^- - \\
 & \partial_\mu \bar{X}^+ X^0) + ig_{s_w} W_\mu^+ (\partial_\mu \bar{Y} X^- - \partial_\mu \bar{X}^+ Y) + ig_{c_w} W_\mu^- (\partial_\mu \bar{X}^- X^0 - \\
 & \partial_\mu \bar{X}^0 X^+) + ig_{s_w} W_\mu^- (\partial_\mu \bar{X}^- Y - \partial_\mu \bar{Y} X^+) + ig_{c_w} Z_\mu^0 (\partial_\mu \bar{X}^+ X^+ - \\
 & \partial_\mu \bar{X}^- X^-) + ig_{s_w} A_\mu (\partial_\mu \bar{X}^+ X^+ - \\
 & \partial_\mu \bar{X}^- X^-) - \frac{1}{2}gM (\bar{X}^+ X^+ H + \bar{X}^- X^- H + \frac{1}{c_w} \bar{X}^0 X^0 H) + \frac{1-2c_w^2}{2c_w} igM (\bar{X}^+ X^0 \phi^+ - \bar{X}^- X^0 \phi^-) + \\
 & \frac{1}{2c_w} igM (\bar{X}^0 X^- \phi^+ - \bar{X}^0 X^+ \phi^-) + igM s_w (\bar{X}^0 X^- \phi^+ - \bar{X}^0 X^+ \phi^-) + \\
 & \frac{1}{2}igM (\bar{X}^+ X^+ \phi^0 - \bar{X}^- X^- \phi^0) .
 \end{aligned}$$



Prvi mobilni telefoni



- Do 1973 (levo); DynaTAC 8000X (desno)
- Masa 790 grama, 25 cm (bez antene), 30 min razgovora i 10 sati punjenja baterije

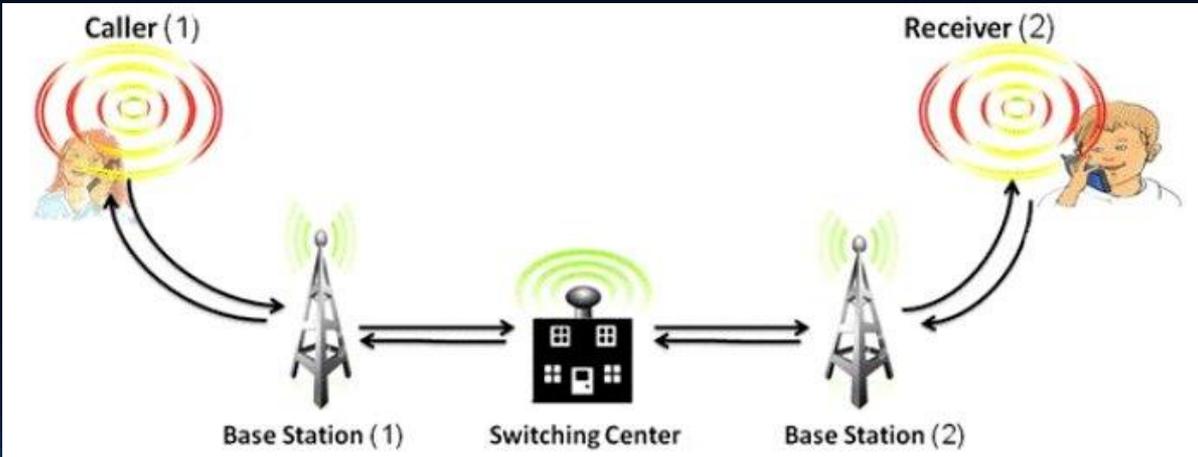
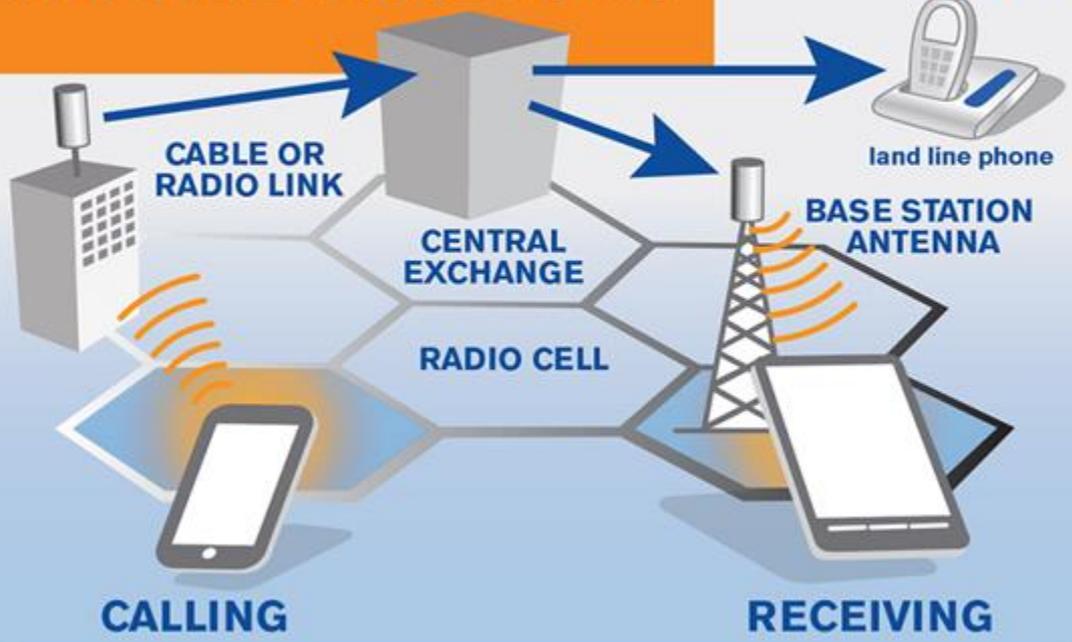
Mobilna mreža

- Analogni sistem mobilnih telefona (1978) u Čikagu
- 1982. – Evropske kompanije – Globalni Sistem Mobilnih komunikacija (GSM)
- 1984 – Motorola DynaTAC prvi komercijalni telefon
- 1995 – GSM prihvaćen u SAD
- 2001 – GSM dostiže udeo od 70% globalne primene
- 2000+ - treća generacija (3G) telefona
- 2007 – Apple revolucija i ekrani na dodir

Prvi (intergalaktički) telefon



HOW MOBILE PHONES WORK



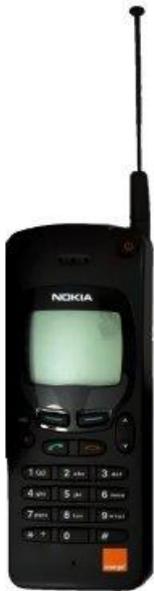
Evolucija telefona



Evolucija mobilnih telefona



Motorola 8900X-2



Nokia 2146



Nokia 3210



Nokia 6210



Ericsson T39



Alcatel OT511



Samsung E250



Apple iPhone



BlackBerry Curve 8900



Samsung Galaxy S2



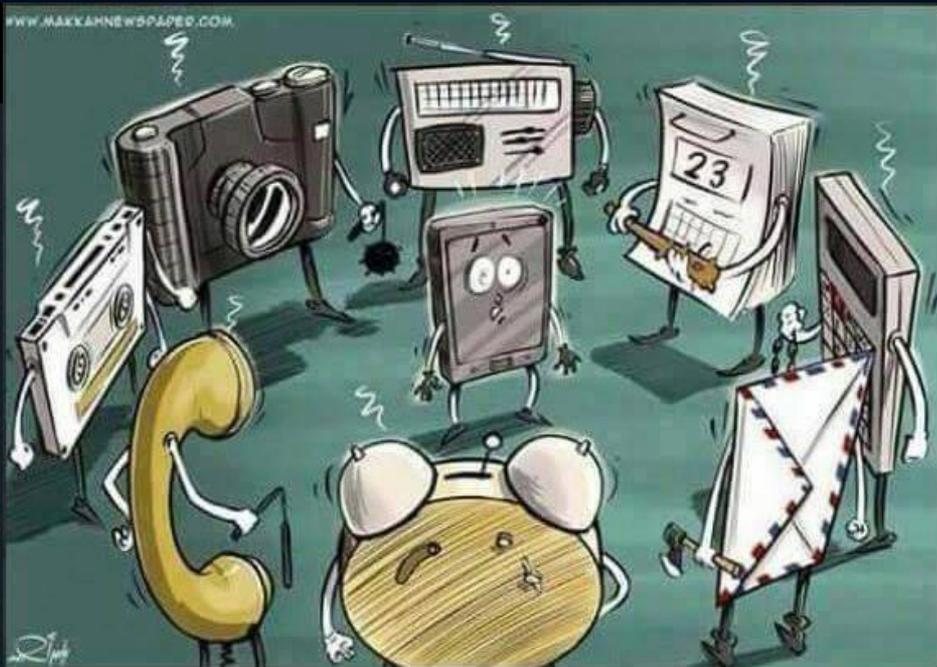
Samsung Galaxy S4



Sony Xperia Z Ultra

Mobilni telefoni danas

*20 years later and all
these things fit in your pocket*



**Znači ti si taj koji nam
je uzeo posao ...**

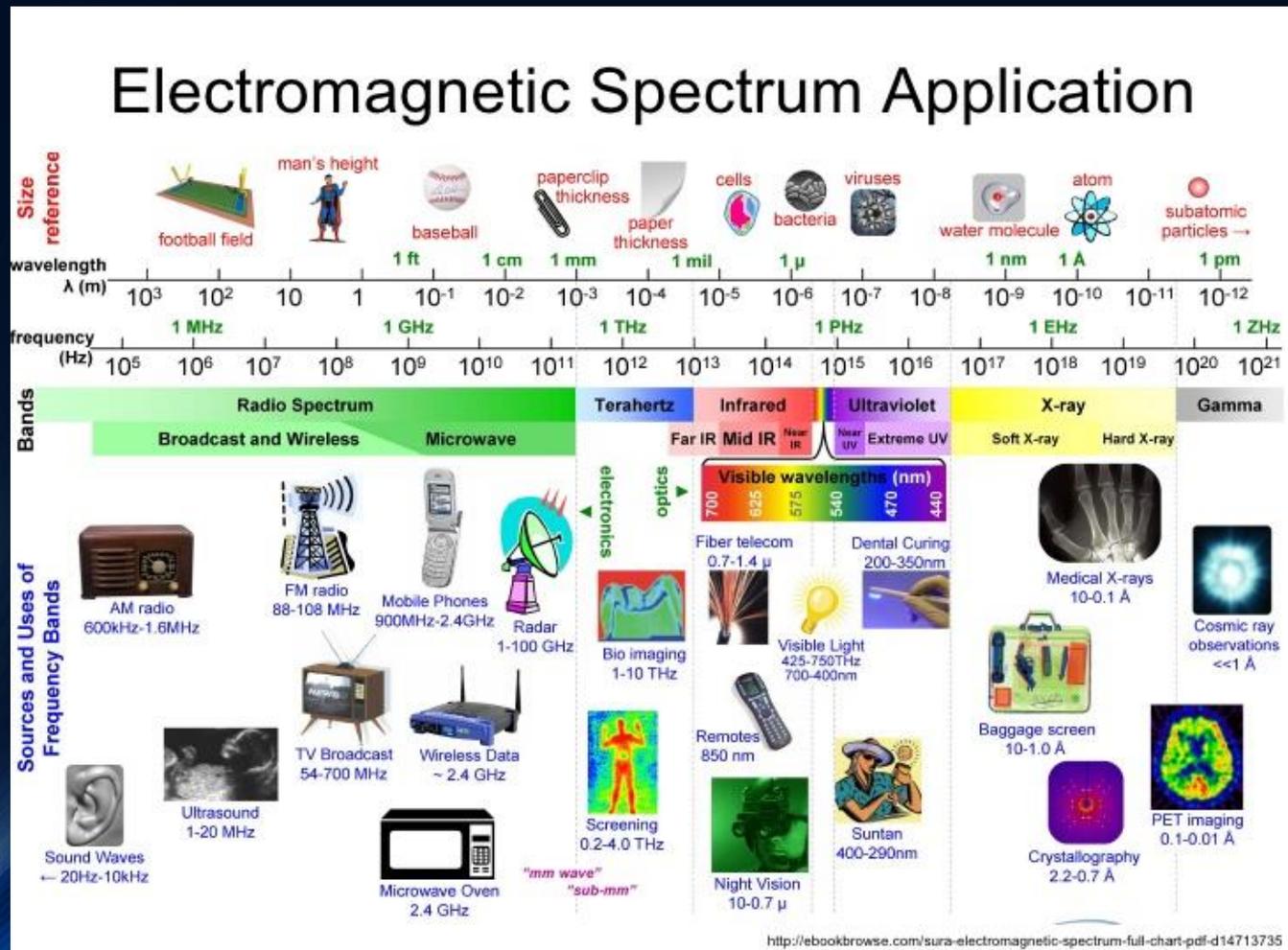
Ipak... ima i onih...



FIZIKA

u i na mobilnom telefonu

Prostiranje talasa



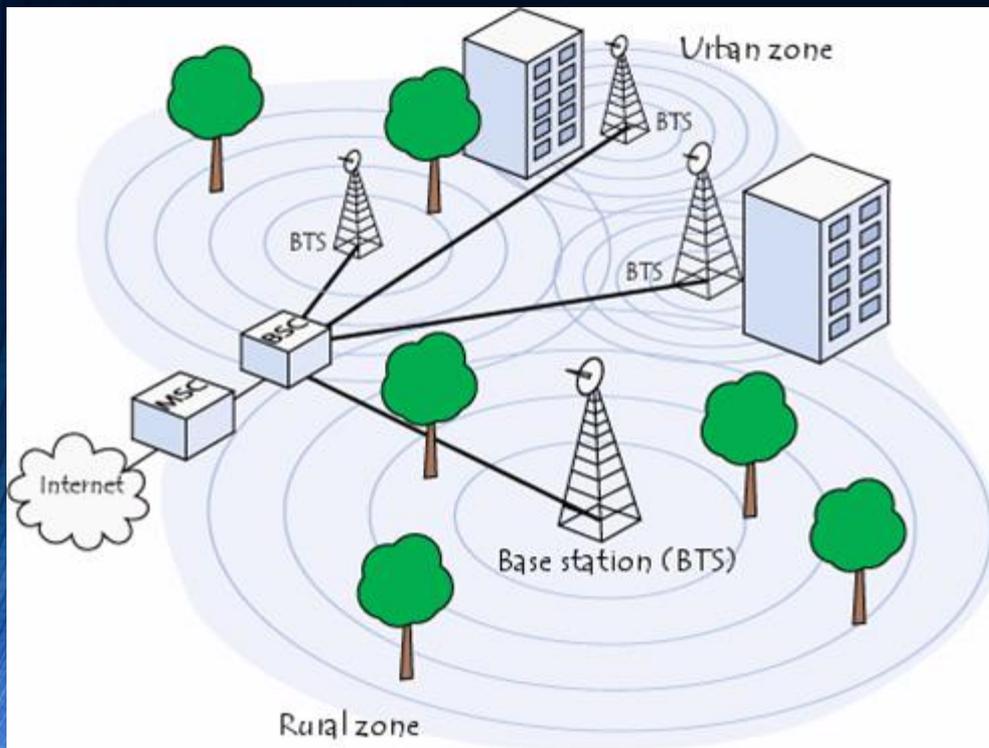
Antena



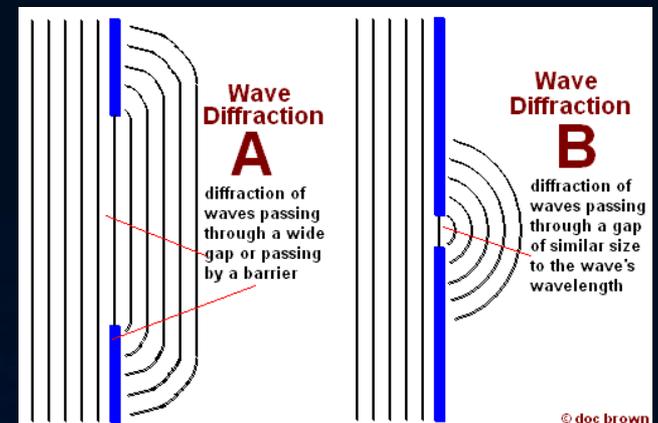
- Toki-voki - jak signal; mobilni – slab signal
- Bazne stanice – 10-50 W, telefoni 2W
 - Snaga opada sa kvadratom rastojanja; 100 puta jači emiter – samo 10 puta veće rastojanje
- Radio i TV predajnici nekoliko desetina-stotina kW



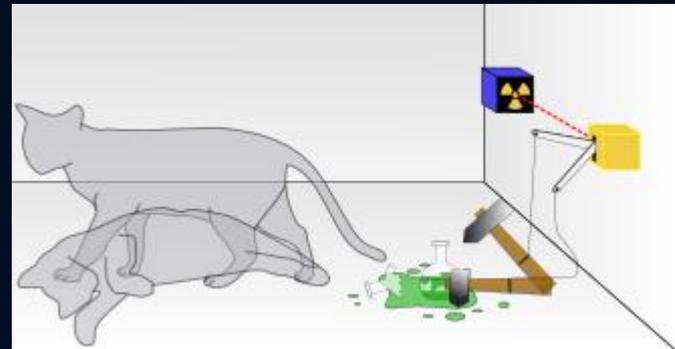
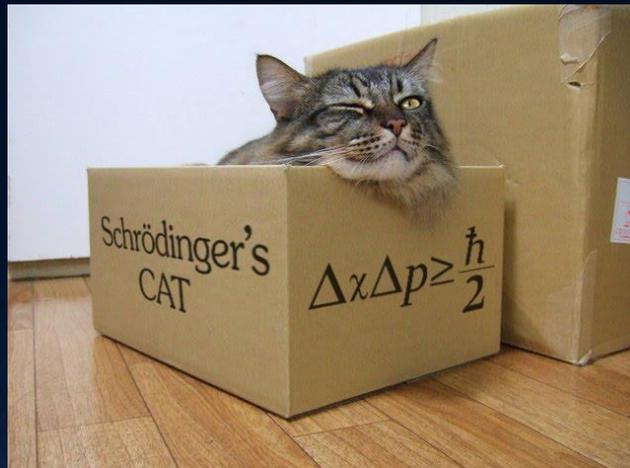
Antena



- Difrakcija



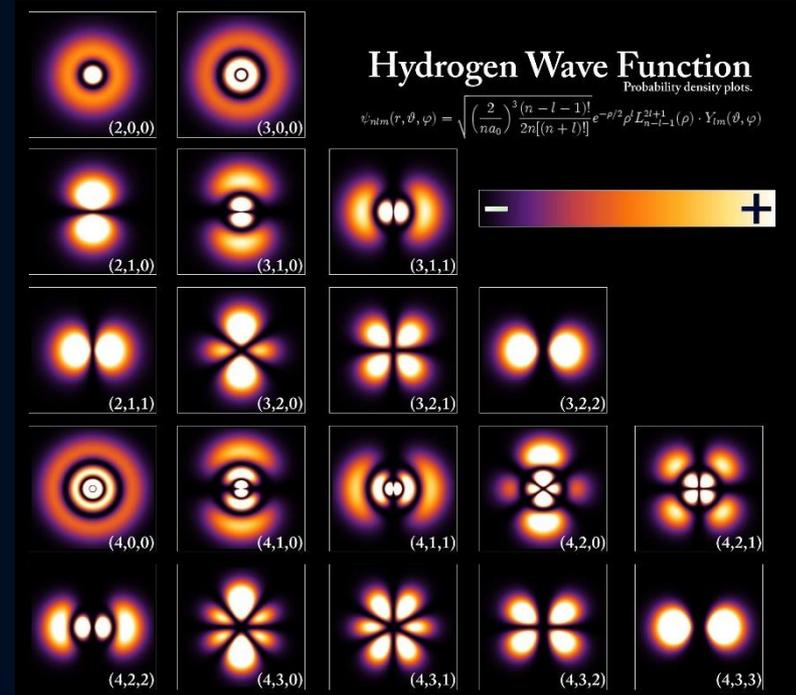
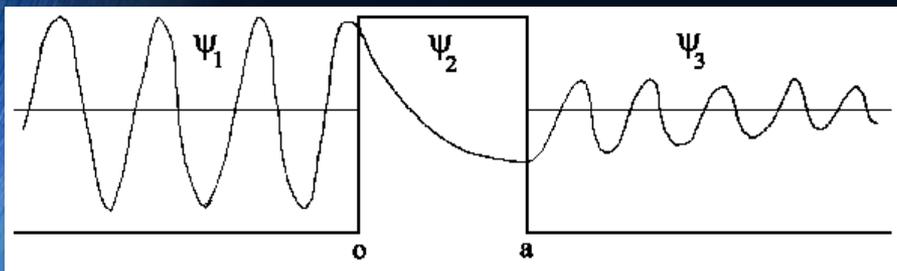
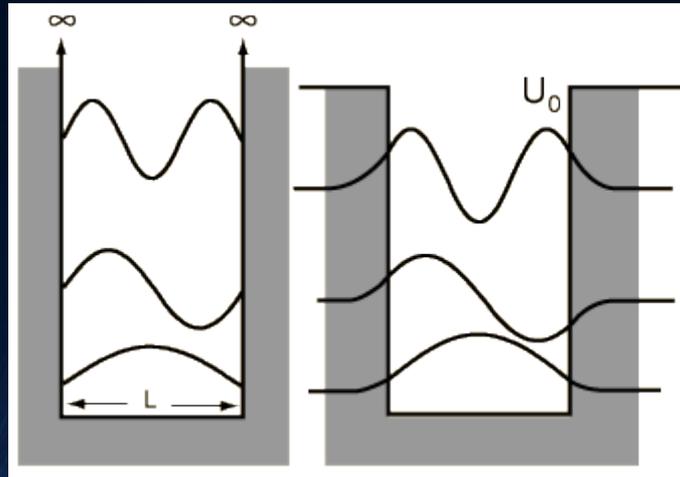
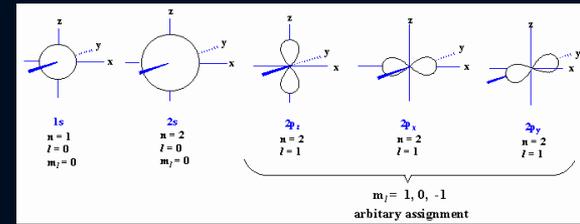
Kvantna teorija



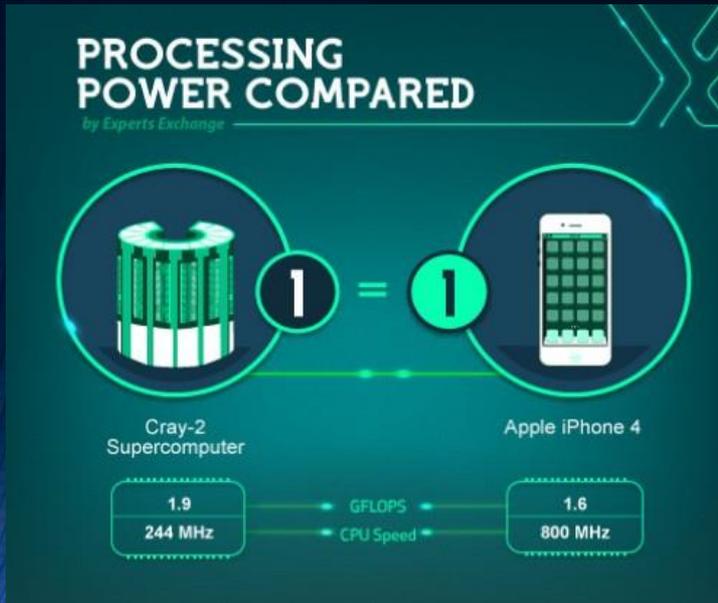
**SCHRÖDINGER'S CAT IS
A LITTLE**

$$\frac{1}{\sqrt{2}}|\text{cat sitting}\rangle + \frac{1}{\sqrt{2}}|\text{cat lying}\rangle$$

Kvantna teorija



Kompjuterska snaga



1985 - 1990

Today's SmartPhones are smart...

With more computing power than Apollo 11 in the pockets of many students, we could take advantage of these devices in science class!



Apollo 11 Moon landing image taken from <http://history.nasa.gov/ap11ann/kippsphotos/apollo.html>

SMART telefoni (senzori...)



14 sensors!

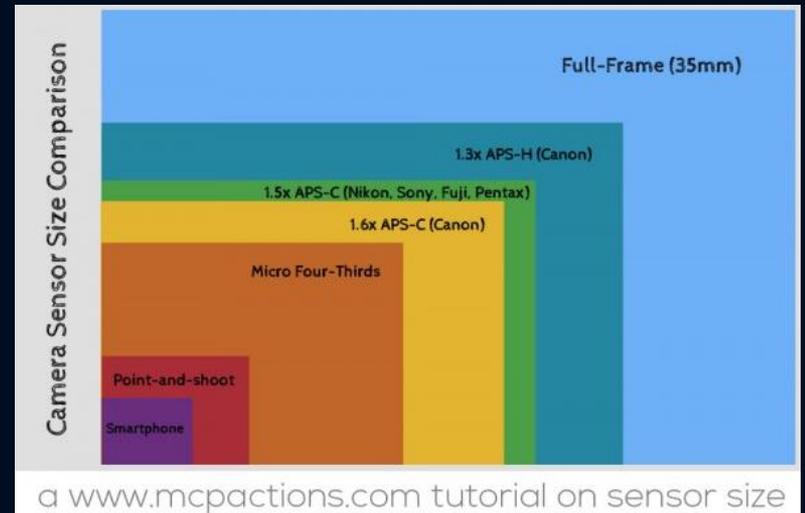
Malo zabave



Selfie (n.):
a picture taken of a person
by that person

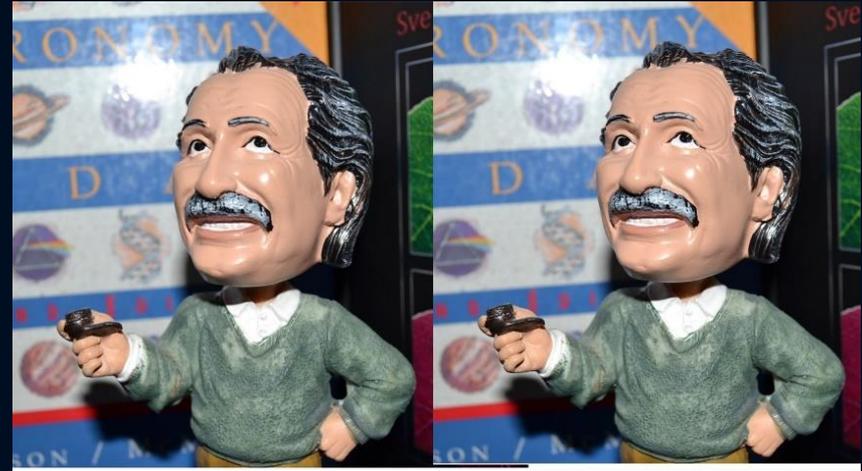


Fotografija



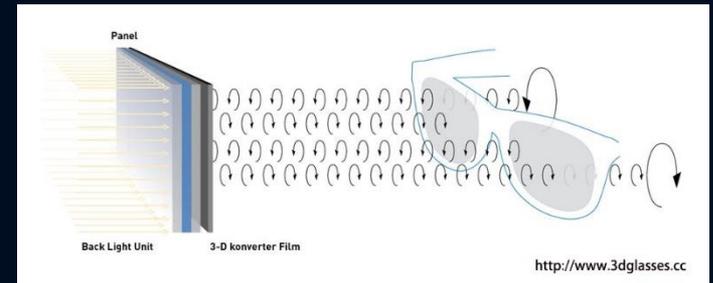
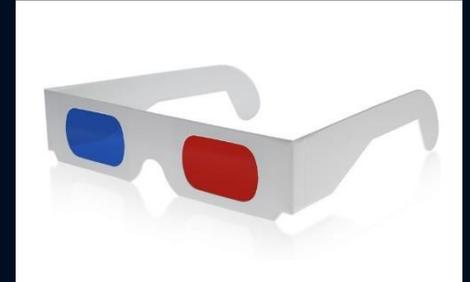
3D fotografije

- Lako je „zbuniti“ oko i mozak
- Levo i desno oko vide sliku koja se malo razlikuje
- „Obradom“ ovih slika mozak stvara sliku 3D prostora
- Ako iskoristimo ovo i svakom oku prikažemo po jednu (2D) fotografiju koje su snimljene malim pomeranjem aparata videćemo 3D fotografiju



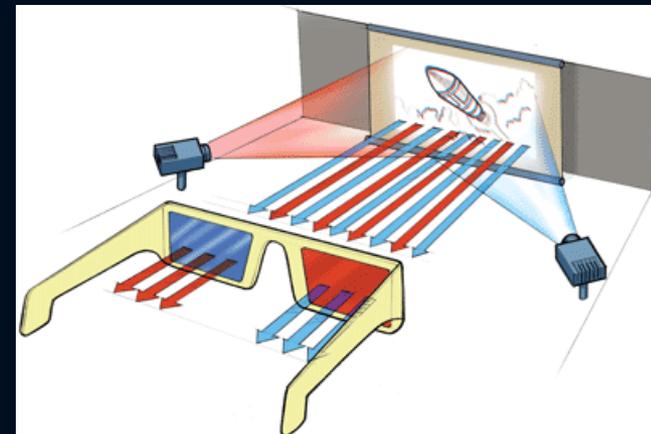
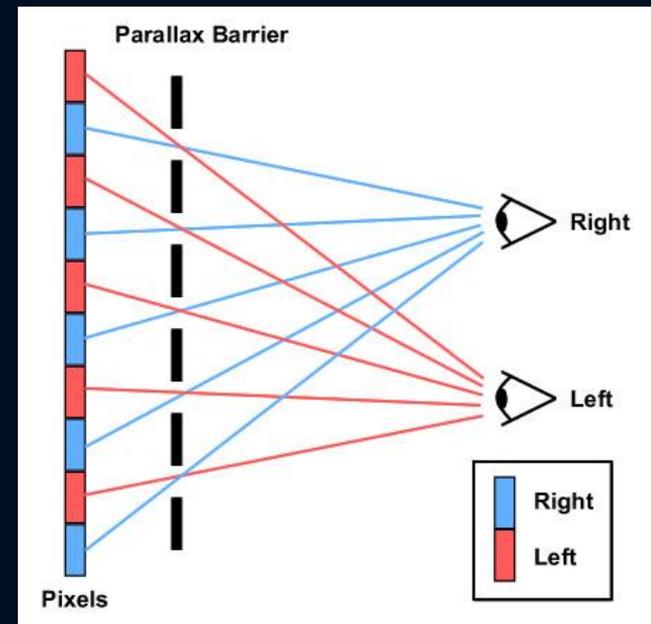
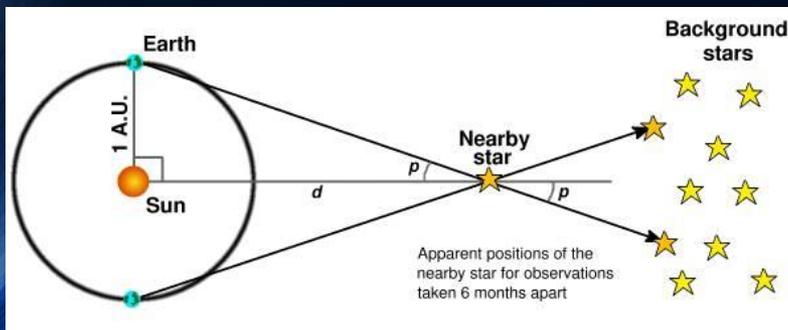
3d fotografije

- 3D fotografije na različite načine:
 - Plavo/crvene naočare
 - Polarizacione naočare
 - VR naočare



3d fotografije

- Princip rada je isti, različita realizacija
 - Odgovarajući filter (boja, polarizacija, sočivo/pregrada) selektuju sliku koja dolazi do levog a koja do desnog oka
 - Istovremenim posmatranjem ove dve fotografije mozak rekonstruiše realan 3D svet
 - Efekat koji je sličan paralaksi



Kako snimiti i gledati



- Šta je potrebno:
 - Fotoapararat ili mobilni telefon
 - VR naočare ili crveno/plave naočare (možete lako da ih napravite – potrebno je samo staklo ili plastika u odgovarajućoj boji ili flomasteri da obojite belu, providnu plastiku)
- Kako:
 - Snimate prvu fotografiju, pomerite malo aparat i snimate drugu, sličnu fotografiju
 - Za VR naočare stavite fotografiju jednu pored druge, za plavo/crvene naočare potreban je program za konverziju (ima ih puno, „googlajte“ reč analygraph 😊)



Analygraph
Za plavo/crvene naočare

<http://instantsolve.net/anaglyph/>



Make It 3D

Za VR ili Google Cardboard naočare



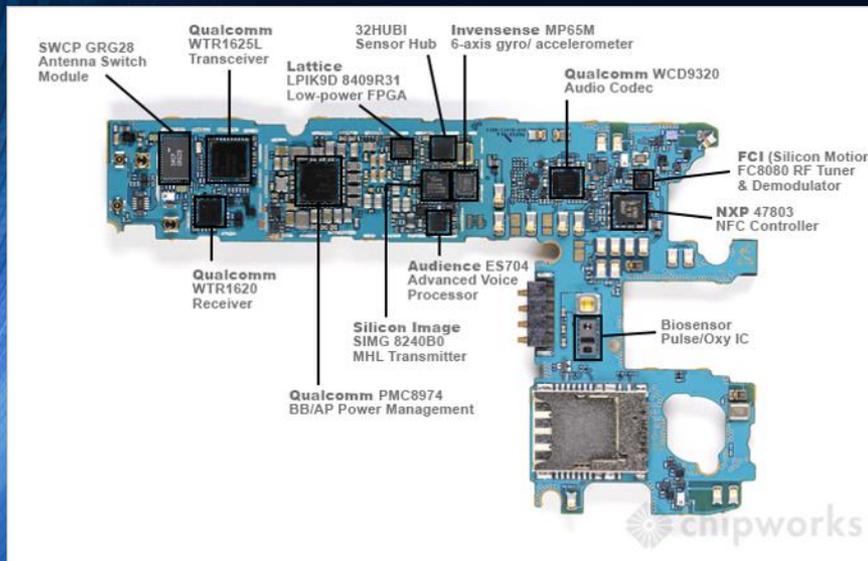
Proširena stvarnost

- eng. *Augmented reality*



Senzori

- 2010 – Galaxy S
- 2011 – Galaxy SII
- 2012 – Galaxy SIII
- 2013 – Galaxy S4
- 2014 – Galaxy S5



Sensor evolution in the SAMSUNG Galaxy S Family



	Galaxy S	Galaxy SII	Galaxy SIII	Galaxy S4	Galaxy S5	Galaxy S6
Accelerometer	+	+	+	+	+	+
Light Meter	+	+	+	+	+	+
GPS	+	+	+	+	+	+
Magnetometer (Compass)	+	+	+	+	+	+
Microphone	+	+	+	+	+	+
Proximity	+	+	+	+	+	+
Battery Temp	+	+	+	+	+	+
Touchscreen	+	+	+	+	+	+
Camera	+	+	+	+	+	+
Cellular Radio	+	+	+	+	+	+
Wifi Radio	+	+	+	+	+	+
Bluetooth	+	+	+	+	+	+
Gyroscope		+	+	+	+	+
NFC			+	+	+	+
Barometer			+	+	+	+
Pedometer				+	+	+
Thermometer				+	-	-
Humidity				+	-	-
Gesture				+	+	+
Color Meter					+	+
Heart Rate					+	+
Fingerprint					+	+
Oxygen Saturation						+
Magnetic Secure Transmission						+

Šta su uopšte to senzori?

- Uređaj koji meri neku fizičku veličinu i rezultat konvertuje u signal koji može da pročita posmatrač ili mašina
- Svaki dan: termometar, otvaranje vrata, kamere, GPS
- I u najstarijim telefonima: mikrofon, tasteri
- Pametni telefoni: tač ekrani, žiroskop, GPS, ubrzanje, kamera

Vrste senzora

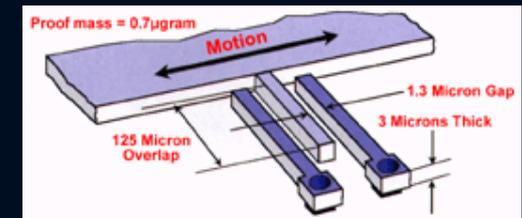
- Rastojanje

- IC predajnik i prijemnik; meri koliko svetlosti se vrati
- Nema mnogo IC izvora pa nema ni smetnji
- Merenje brzine i rastojanja (laseri, mikrotalasi itd)
- Sličan princip: ultrazvučni senzori – sonar

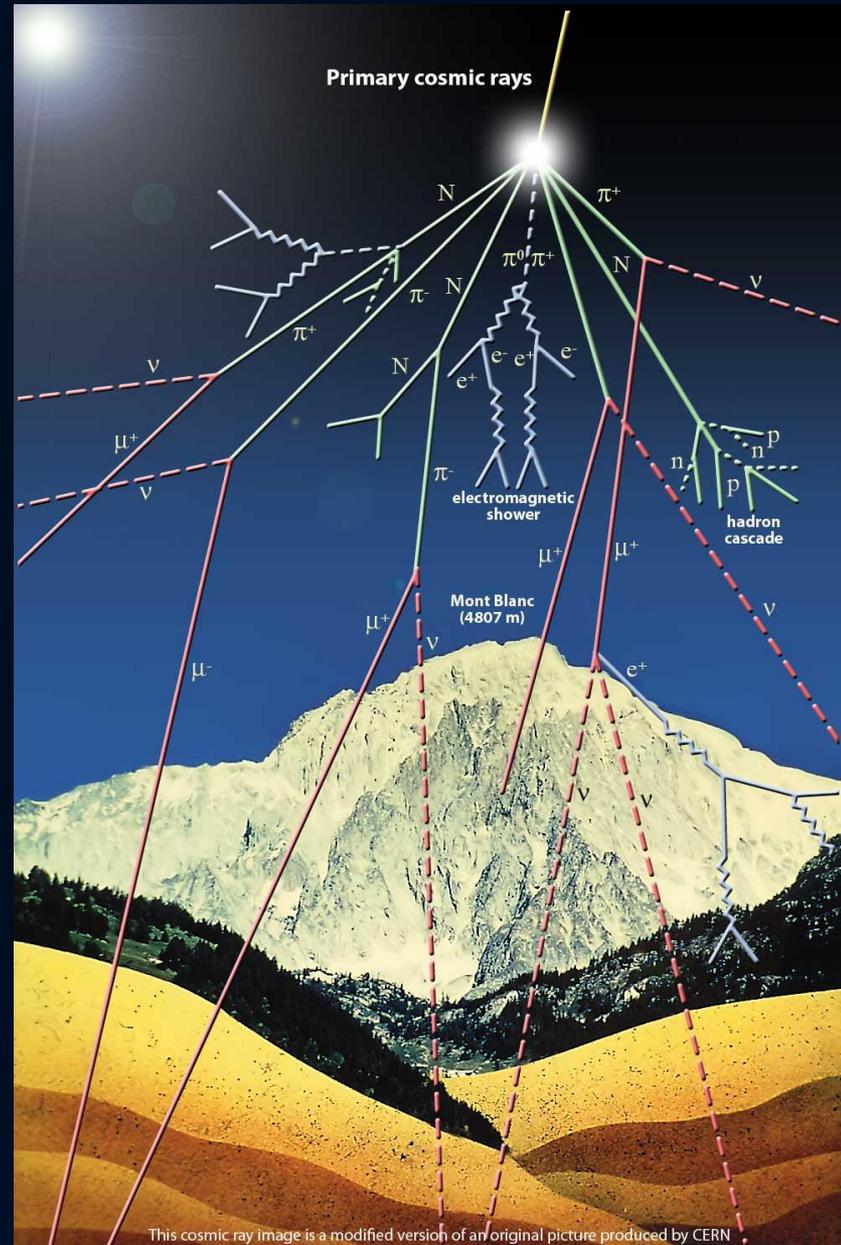
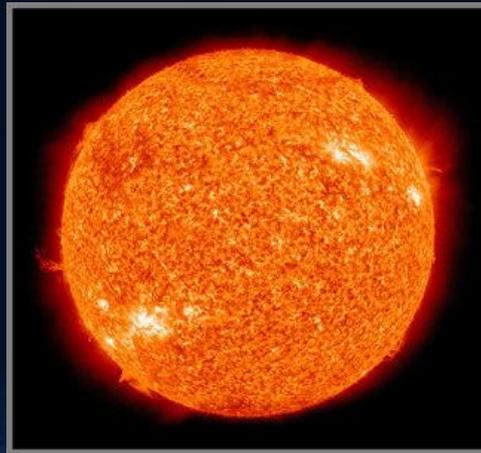
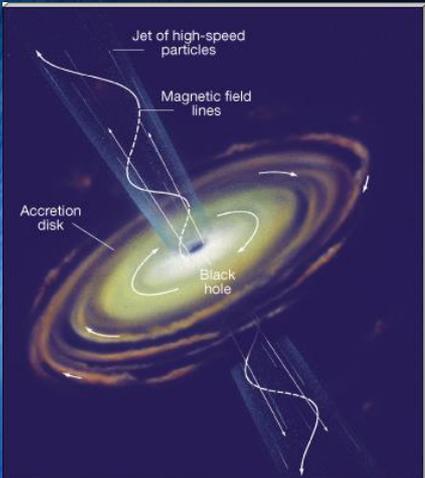


- Ubrzanje i žiroskop

- Promena brzine u 2 ili 3 prostorne dimenzije
- Meri se brzina promena kapaciteta kondenzatora i prevodi u ubrzanje
- Žiroskop – koriolisova sila: kreće duž jedne ose, rotira duž druge, javlja se sila duž treće ose

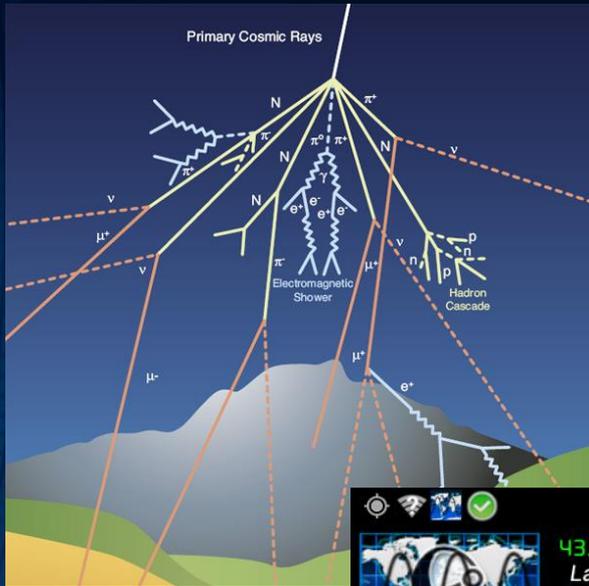


Kosmičko zračenje



This cosmic ray image is a modified version of an original picture produced by CERN.

Projekat DECO



6:43 PM

43.07515° Latitude -89.40767° Longitude
238.00m Altitude 293° Bearing

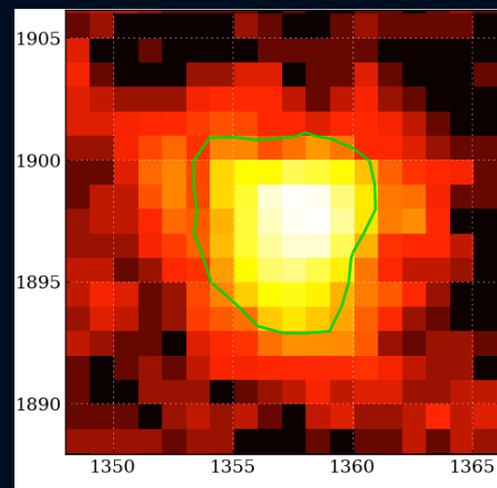
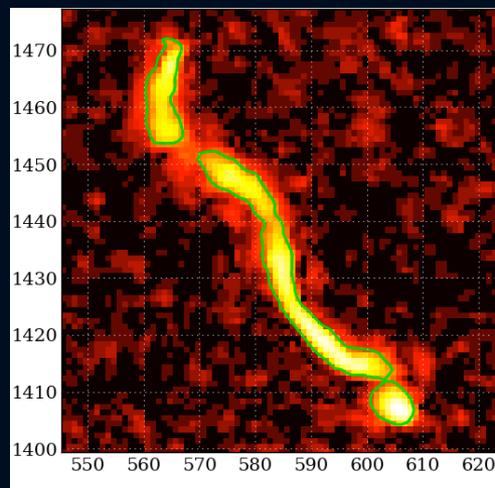
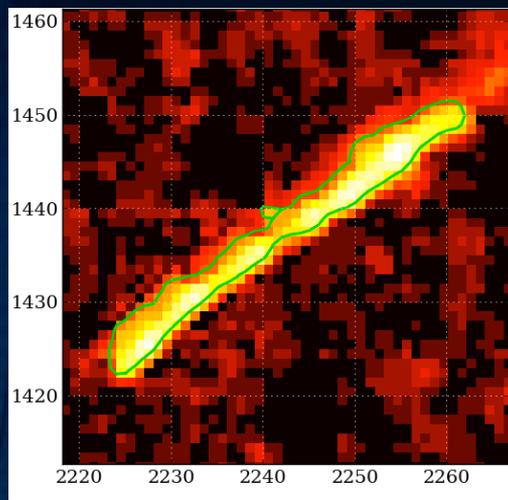
Device Id: 00000000-7f71-62fb-f647-baf70033c587
Status: Scanning
Battery: 90% (32.0°C / 89.6°F) discharging
RGB Noise: (99,99,99)

Samples	Candidates	Events
2292781	310	142
Count	Count	Count
1.6 sec	---	---
Rate	Rate	Rate

Orientation: -3° / -5° / 293°
Magnetic Field (μ T): 29 / 7 / -51

- Snima fotografije 1-2 sekunde
- Dovoljno sjajnih piksela – kandidat
- Nova analiza – proverava događaj
- Kosmičko zračenje – mioni
 - Drugi događaji: elektroni, gama zraci, alfa čestice (radioaktivno zračenje okoline)
- Nekoliko događaja za 24h

Projekat DECO - događaji



- Mion, kosmičko zračenje
- Elektron (radioaktivno zračenje, direktno ili gama zračenje koje je “pogodilo” elektron)
- Elektron ili gama zračenje

Navigacija – na nebu

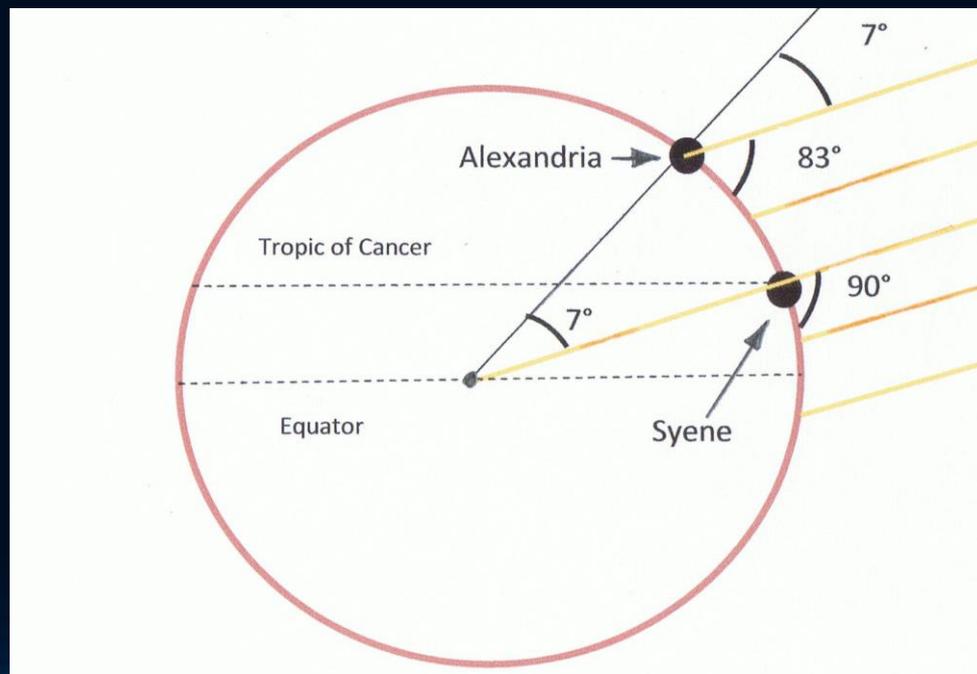


A sada - rešenje

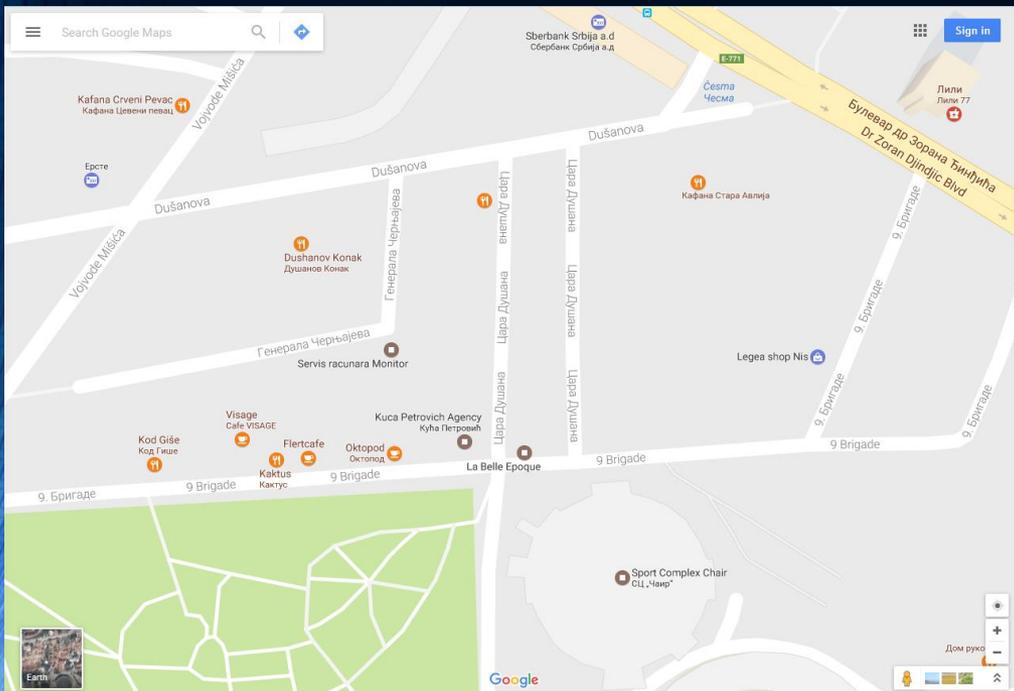


Obim Zemlje

- Eratosten (276 p.n.e. - 194 p.n.e.)
- Sijena – prvi dan leta, u podne, Sunce tačno iznad
- Aleksandrija – senka!
- Razlika – 7°
- Rastojanje $7/360^\circ$



Ili mobilni telefon & Google Map ☺



$$\phi_1 = 43.317254$$

$$\phi_2 = 43.318517$$

$$\Delta\phi = |\phi_1 - \phi_2| = 0.001263$$

$$s = 150\text{m}$$

$$L = 2\pi R = \frac{360^\circ \cdot s}{\phi} \approx 42755,3\text{km}$$

$$R = 6800\text{km}$$

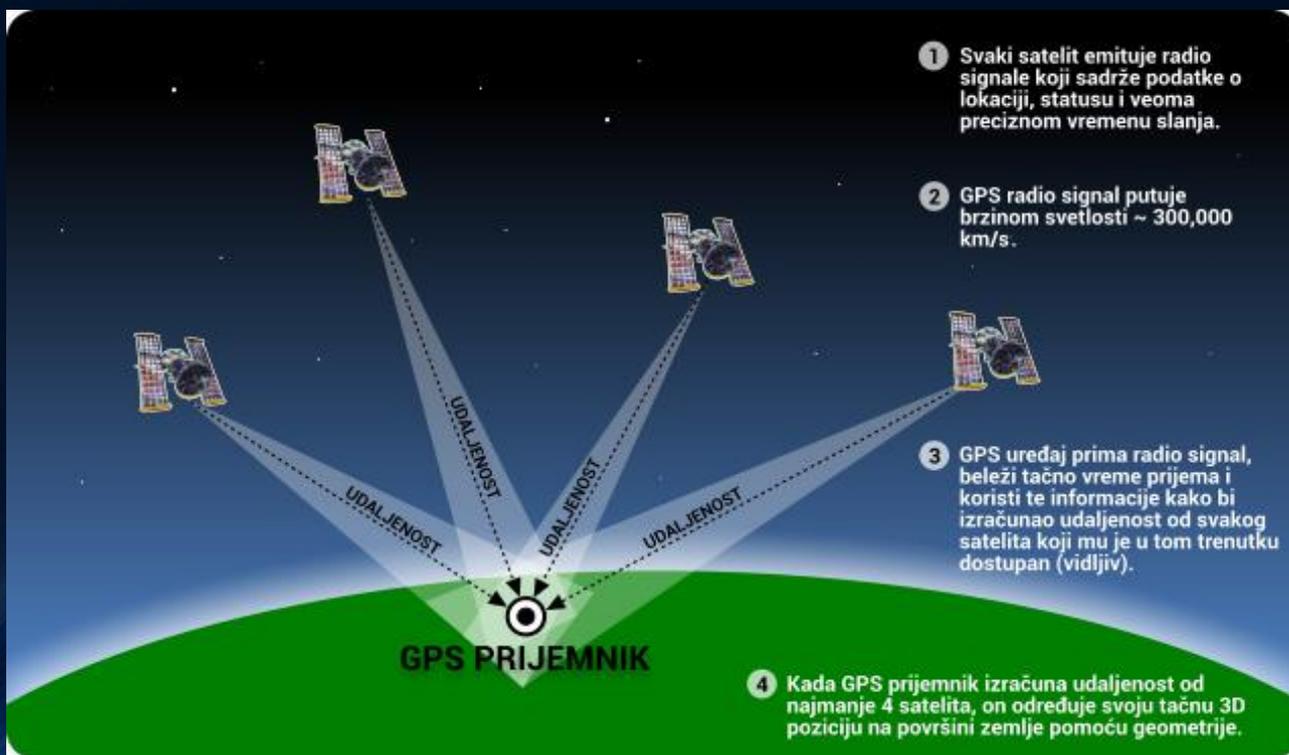
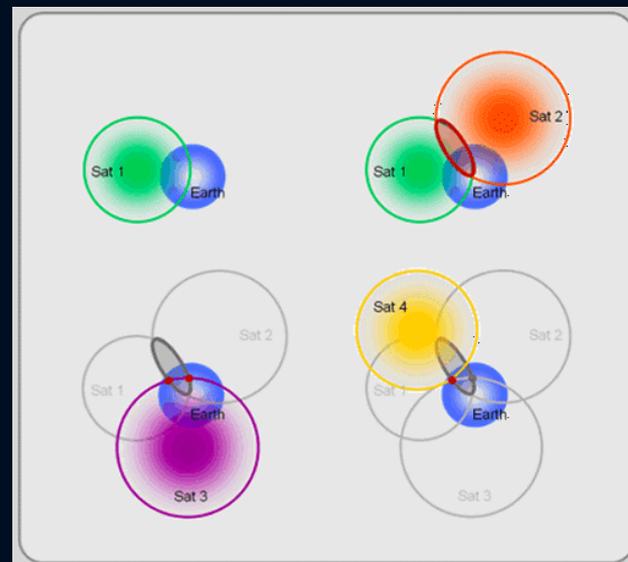
Navigacija – na Zemlji



Globalni pozicioni sistem (GPS)

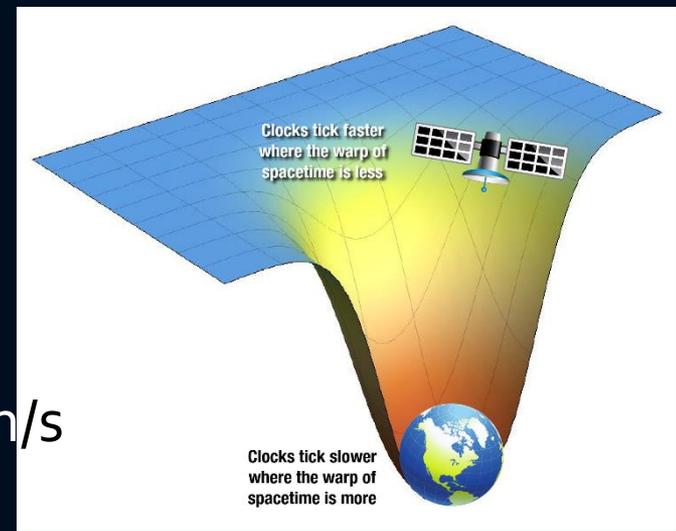
- Tri sistema:
 - U vasioni, Kontrolni, Korisnički
- Blok I – lansirani 1978-85, svi van funkcije
- Blok II – 24 GPS satelita, 6 orbitalnih ravni, ravnomerno raspoređeni i nagnutih pod uglom od 55 u odnosu na ekvatorijalnu ravan – NE rotiraju
- Svaka orbita po 4 satelita, skoro kružne; prečnik 4 puta veći od prečnika Zemlje
- Stanice za praćenje: Havaji, Kolorado, Kvajlin ostrvo, Aknezijsko ostrvo; ažuriranje dva puta dnevno

Globalni pozicioni sistem (GPS)



Ajnštajn i GPS

- Visina: 20000 km, brzina 14000 km/s
- Svaki satelit – atomski časovnik:
 - Impuls sa tačnošću od 1 nanosekunde
- Položaj određuje sa tačnošću od 5-10 m (20-40 ns)
- VREME JE RELATIVNO !!!
 - STR: 7 mikrosekundi sporije na dan (na satelitu)
 - GTR: 45 mikrosekundi sporije na dan (na Zemlji)
- Bez teorije relativnosti GPS bi postao neupotrebljiv posle samo 2 minuta! (greška 38000 ns /dan)

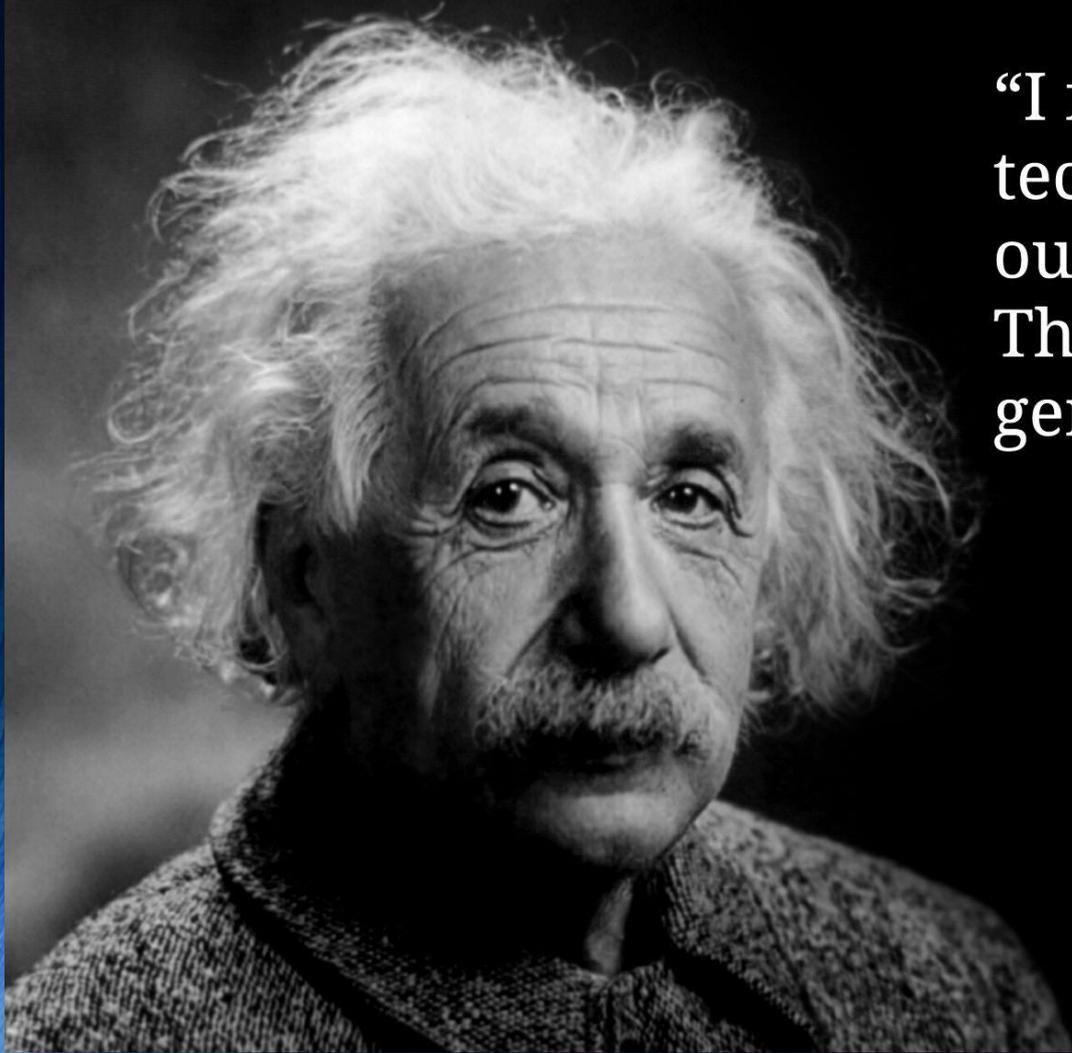


$$T = \frac{T_0}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$T = \frac{T_0}{\sqrt{1 - \frac{2GM}{Rc^2}}}$$

$$1s = 10^3ms = 10^6\mu s = 10^9ns$$

$$1s = 1000ms = 1.000.000\mu s = 1.000.000.000ns$$



“I fear the day that
technology will surpass
our human interaction.
The world will have a
generation of idiots.”

Albert Einstein

Šta je telefon zamenio?





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